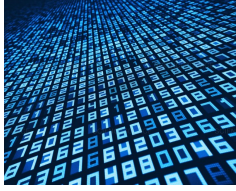


**Describing data**

Samples and populations are often made of lots of individual (observational) units and their associated information (observations, variables).

We need to be able to describe samples by summary statistics (mean, median, variance, etc) so that these summaries can serve as an estimate of the same summaries for their statistical populations.




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1

**How do measures of location (mean versus median) and spread (standard deviation versus interquartile range) compare?**

**Disarming fish**  
(protection against predation)



Threespine stickleback  
(Gasterosteus aculeatus)

**Plate Genotypes**  
Ectodysplasin (Eda) locus  
(3<sup>rd</sup> generation)

**MM (marine)**

**Mm (hybrid)**

**mm (freshwater)**

Variation is at the heart of biology! The diversity among individuals and species forms the foundation of biological science

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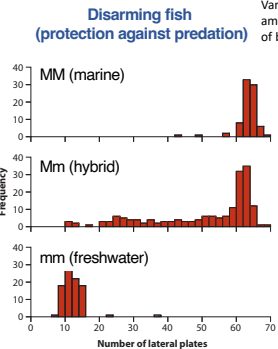
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2

**How do measures of location (mean versus median) and spread (standard deviation versus interquartile range) compare?**

**Disarming fish**  
(protection against predation)



Variation is at the heart of biology! The diversity among individuals and species forms the foundation of biological science

**Which distribution is more asymmetric?**

Whitlock & Schluter, The Analysis of Biological Data, 3e © 2020 W. H. Freeman and Company

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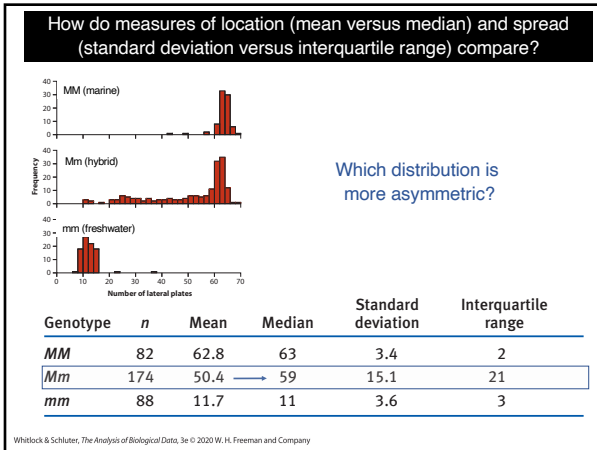
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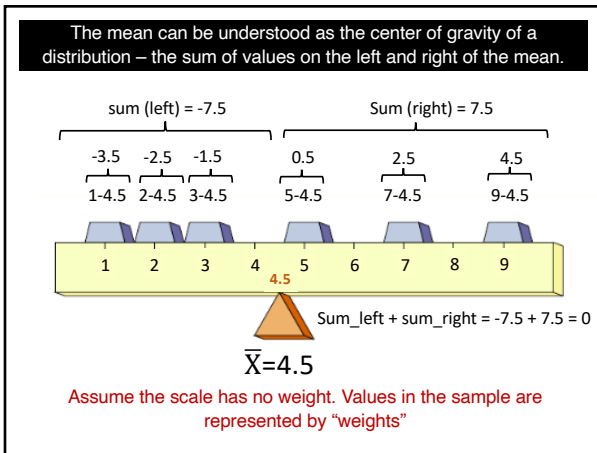
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Recall from lecture 5: the sum of deviations from the mean is always zero, making the mean the 'center of gravity' of a distribution.

Quantities needed to calculate the standard deviation and variance of snake undulation rate ( $\bar{Y} = 1.375 Hz$ ).

Observations ( $Y_i$ )	Deviations ( $Y_i - \bar{Y}$ )	Squared deviations ( $Y_i - \bar{Y}$ ) <sup>2</sup>
0.9	-0.475	0.225625
1.2	-0.175	0.030625
1.2	-0.175	0.030625
1.3	-0.075	0.005625
1.4	0.025	0.000625
1.4	0.025	0.000625
1.6	0.225	0.050625
2.0	0.625	0.390625
Sum	0.000	0.735

Whitlock & Schluter, The Analysis of Biological Data, 3e © 2020 W. H. Freeman and Company

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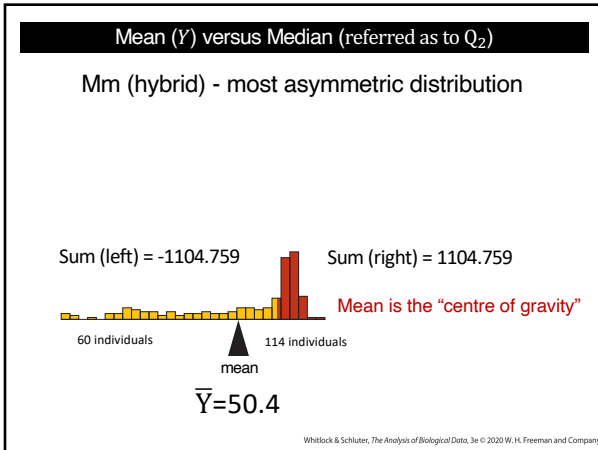
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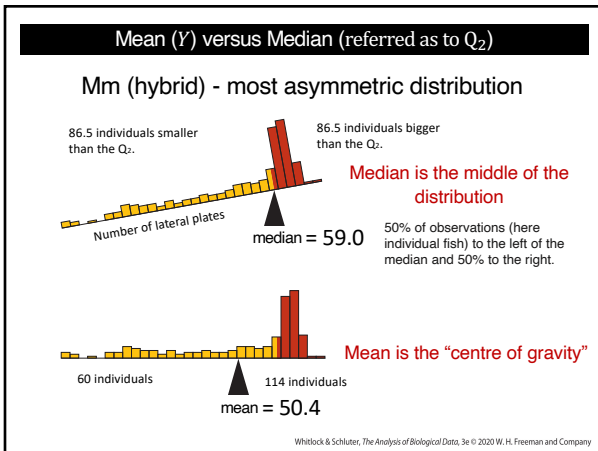
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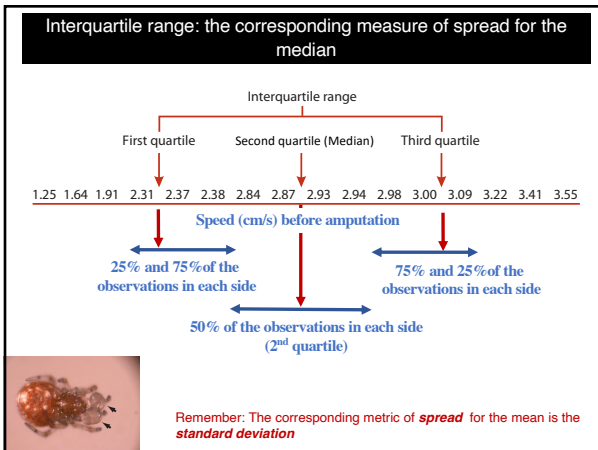
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**Interquartile range: the corresponding measure of spread for the median**

Speed (cm/s) before amputation

25% and 75% of the observations in each side

75% and 25% of the observations in each side

50% of the observations in each side (2<sup>nd</sup> quartile)

It's crucial to understand what the first, second (median), and third quartiles represent, and how the median differs from the mean. However, I don't expect you to calculate them by hand. Still, it's important to show some of these calculations, as it helps improve numeracy.

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**Interquartile range: the corresponding measure of spread for the median**

Speed (cm/s) before amputation

While the calculation of the median (2nd quartile or Q2) differs depending on whether the number of observations is odd or even, the calculations for the 1st (Q1) and 3rd (Q3) quartiles remain the same.

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**Interquartile range: the corresponding measure of spread for the median**

Speed (cm/s) before amputation

Positioning  $Q_1$ :  $j = 0.25n = (0.25)(16) = 4$

where  $n$  is the number of observations in the data (i.e., 16 male spiders).

Because here  $j$  is an integer (i.e., whole number, not a fraction), then the 1<sup>st</sup> quartile is the average of  $Y_{(j)}$  and  $Y_{(j+1)} = Y_{(4)}$  and  $Y_{(4+1)} = (2.31 + 2.37) / 2 = 2.340$  cm/s

**First quartile ( $Q_1$ ) = 2.340 cm/s**

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Interquartile range: the corresponding measure of spread for the median

Speed (cm/s) before amputation

This is not exactly the default rule in R, but the values are very similar. There are several different rules for calculating quartiles.

**First quartile ( $Q_1$ ) = 2.340 cm/s**

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13

Interquartile range: the corresponding measure of spread for the median

Speed (cm/s) before amputation

If  $j$  was not an integer, round  $j$  (e.g., say  $j$  was 4.32 then round  $j = 4$ ). We would then have picked the 4<sup>th</sup> value in the ranked distribution (i.e., 2.31 cm/s)

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14

Interquartile range: the corresponding measure of spread for the median

Speed (cm/s) before amputation

Positioning  $Q_3$ :  $j = 0.75n = (0.75)(16) = 12$   
 where  $n$  is the number of observations. If  $j$  is an integer (whole number, not a fraction), then the 3<sup>rd</sup> quartile is the average of  $Y_{(j)}$  and  $Y_{(j+1)} = Y_{(12)}$  and  $Y_{(12+1)} = (3.00 + 3.09) / 2 = 3.045$  cm/s

**Third quartile ( $Q_3$ ) = 3.045 cm/s**

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15

**Interquartile range: the corresponding measure of spread for the median**

Speed (cm/s) before amputation

If  $j$  was not an integer, round  $j$  (e.g., say  $j$  was 12.72 then  $j = 13$ ). We would then have picked the 13<sup>th</sup> value in the ranked distribution (i.e., 3.09 cm/s)

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16

**Interquartile range: the corresponding measure of spread for the median**

$Q_1 = 2.340$        $IQR = 0.705 (Q_3 - Q_1)$        $Q_3 = 3.045$

Speed (cm/s) before amputation

The **interquartile range** (IQR) for the speed data before amputation is then  $Q_3 - Q_1 = 3.045 - 2.340 = 0.705$  cm/s

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**Remember: the mean reflects all values in a distribution but is influenced by extreme values. The median, while not as representative of the entire distribution, is resistant to the influence of extreme values.**

$Y = 53, 58, 62, 64, 68, 72, 73, 77, 86, 87, 88, 92$

$\bar{Y} = 73.3$

$Q_2 = 72.5$

$Y = 53, 58, 62, 64, 68, 72, 73, 77, 86, 87, 88, 192$

$\bar{Y} = 81.7$

$Q_2 = 72.5$

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Let's take a "power break" – 1 minute



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The median is the middle measure of a set of observations (distribution)


If the number of observations ( $n$ ) is **even**, then the median is calculated differently:



It gives an "arm" (or a pedipalp) for a female spider.

Running speed (cm/s) of male *Tidarren* spiders before and after voluntary amputation of one pedipalp.

Spider	Speed before	Speed after	Spider	Speed before	Speed after
1	1.25	2.40	9	2.98	3.70
2	2.94	3.50	10	3.55	4.70
3	2.38	4.49	11	2.84	4.94
4	3.09	3.17	12	1.64	5.06
5	3.41	5.26	13	3.22	3.22
6	3.00	3.22	14	2.87	3.52
7	2.31	2.32	15	2.37	5.45
8	2.93	3.31	16	1.91	3.40



*Oxyopes salticus*

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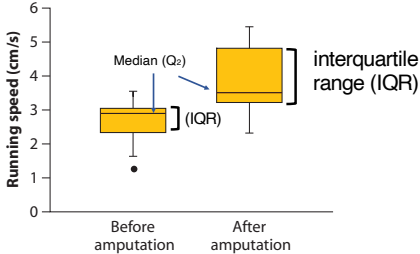
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Representing data distributions by their quartiles:  
Boxplot (box-and-whisker plot)




Running speed (cm/s)

Median ( $Q_2$ )

interquartile range (IQR)

Before amputation

After amputation



John Tukey  
(box-and-whisker 1977)

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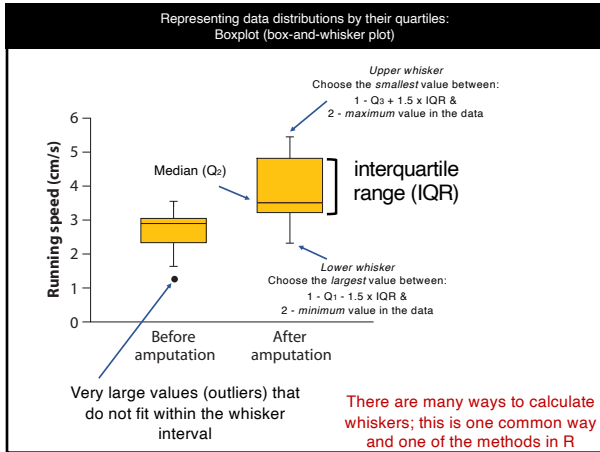
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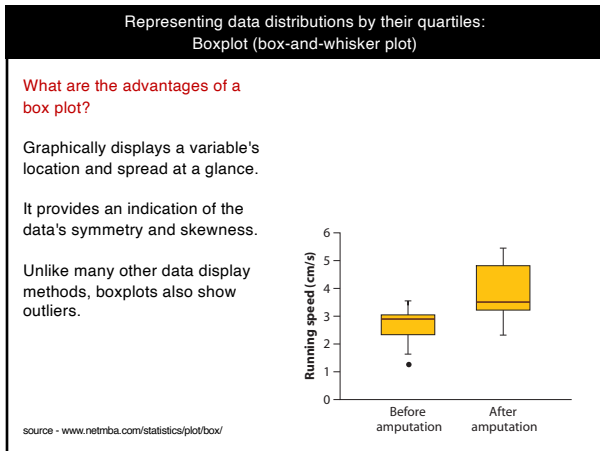
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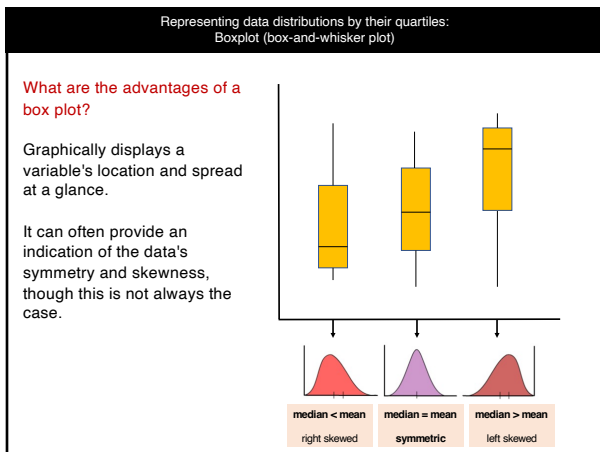
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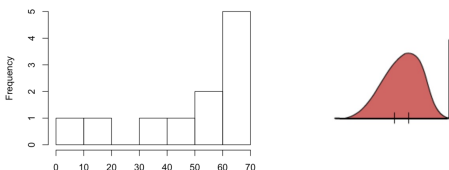
24



Representing data distributions by their quartiles:  
Boxplot (box-and-whisker plot)

Three fictional data sets to illustrate the calculation and properties of distributions using their boxplots (shown in the next slide) – can you spot their differences?

Left-skewed distribution: 9,11,31,44,52,58,61,61,63,64,66



The histogram shows a distribution with a long tail on the left side. The x-axis ranges from 0 to 70, and the y-axis (Frequency) ranges from 0 to 5. The density plot is a red curve that is skewed to the left, with a peak around 50 and a long tail extending to the left.

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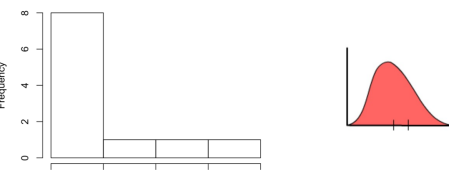
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Representing data distributions by their quartiles:  
Boxplot (box-and-whisker plot)

Three fictional data sets to illustrate the calculation and properties of distributions using their boxplots (shown in the next slide) – can you spot their differences?

Right-skewed distribution: 1,2,3,4,5,6,7,10,20,30,40



The histogram shows a distribution with a long tail on the right side. The x-axis ranges from 0 to 40, and the y-axis (Frequency) ranges from 0 to 8. The density plot is a red curve that is skewed to the right, with a peak around 5 and a long tail extending to the right.

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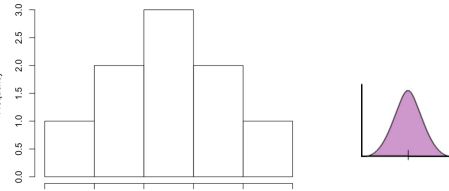
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Representing data distributions by their quartiles:  
Boxplot (box-and-whisker plot)

Three fictional data sets to illustrate the calculation and properties of distributions using their boxplots (shown in the next slide) – can you spot their differences?

Symmetric distribution: 1,3,3,4,4,4,5,5,6



The histogram shows a symmetric distribution with a bell-shaped curve. The x-axis ranges from 1 to 6, and the y-axis (Frequency) ranges from 0.0 to 3.0. The density plot is a purple curve that is symmetric and bell-shaped, centered around 3.5.

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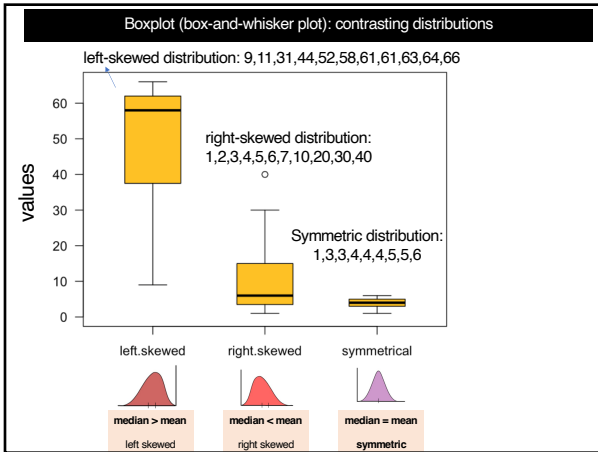
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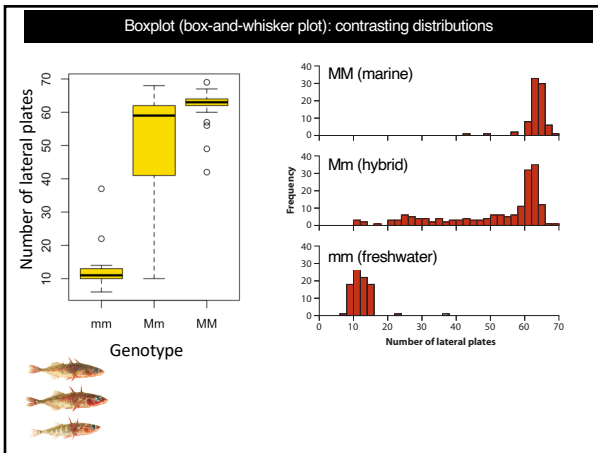
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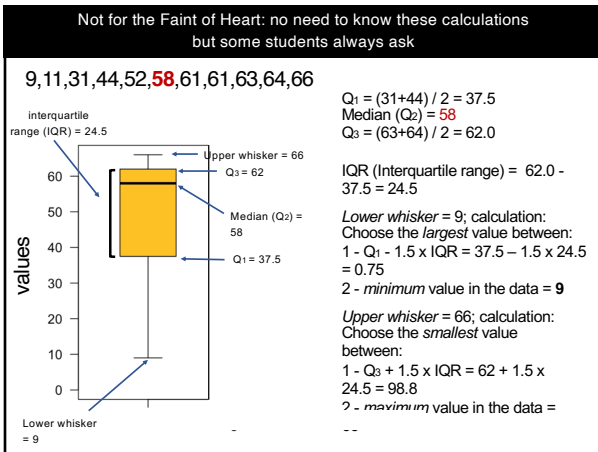
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**Statistics is based on samples!**

The primary goal of statistics is to estimate (infer) an unknown quantity of an entire population based on sample data.

Statistics is the science of making decisions with incomplete knowledge, using samples to represent populations that often have unknown sizes.

However, sample quantities (mean, median, standard deviation, etc.) vary from sample to sample, introducing a level of uncertainty.

**Next lecture - Estimating with uncertainty**

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